

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	64	"4402053"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/09/20 13:44
S2	5	("4402053") or ("6597971").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/09/20 13:44
S3	64	("3804270" "3888362" "3986007" "4017721" "4146924" "4187051" "4271477" "4305130").PN. OR ("4402053"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 13:54
S4	0	S3 and image same mov\$3 same release with position	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 13:54
S5	27	S3 and image same mov\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 13:55
S6	18	S3 and image with mov\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:00
S7	0	observe same workpiece same without with stop\$3 with robot	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:01
S8	1	observe same workpiece same stop\$3 with robot	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:02
S9	0	estimat\$3 with workpiece with pose same visual with sensor	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:02
S10	0	estimat\$3 with workpiece with pose and visual with sensor	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:03
S11	121403	workpiece	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:03
S12	1133	workpiece same estimat\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:03
S13	6	workpiece same estimat\$3 same pose	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:03

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S14	6	workpiece same estimat\$3 same (pose or position) and visual with sensor	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:22
S15	81	robot and visual with sensor same workpiece	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:51
S16	86	image same workpiece same mov\$3 same robot	US-PGPUB; USPAT; USOCR	OR	ON	2007/09/20 14:51